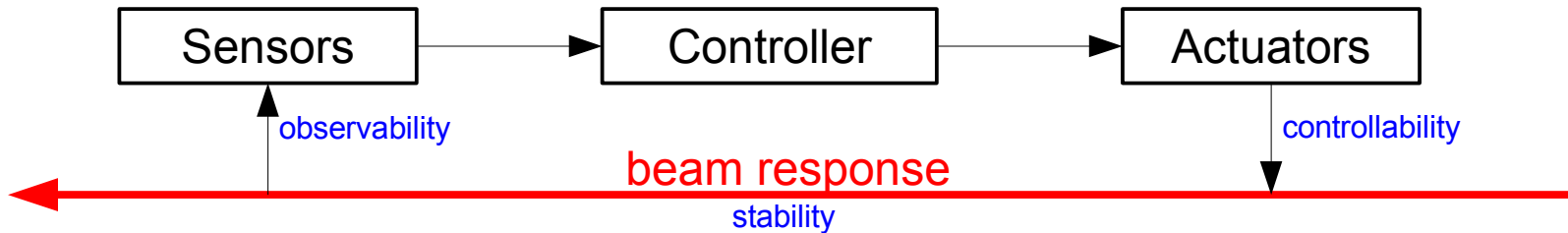


On the Feasibility of (semi-) automated Tune Control in the PS

Ralph J. Steinhausen

**with special thanks for their input to
A. Boccardi, R. Garoby, M. Gasior, S. Gilardoni,
J.J. Gras, Y. Papaphilippou, R. Steerenberg**

- AB Management Board Meeting discussion (2007-08-13):
 - “Further tests were carried out on the pole face windings during the week and some higher frequency perturbations (100, 150 and 200Hz*) were observed in the beam. “
 - “S. Myers asked R. Garoby (for the BI group) to *investigate the feasibility and the potential bandwidth of a closed loop control of the tune in the PS.*”
 - (*minimised through power-converter controller optimisation)

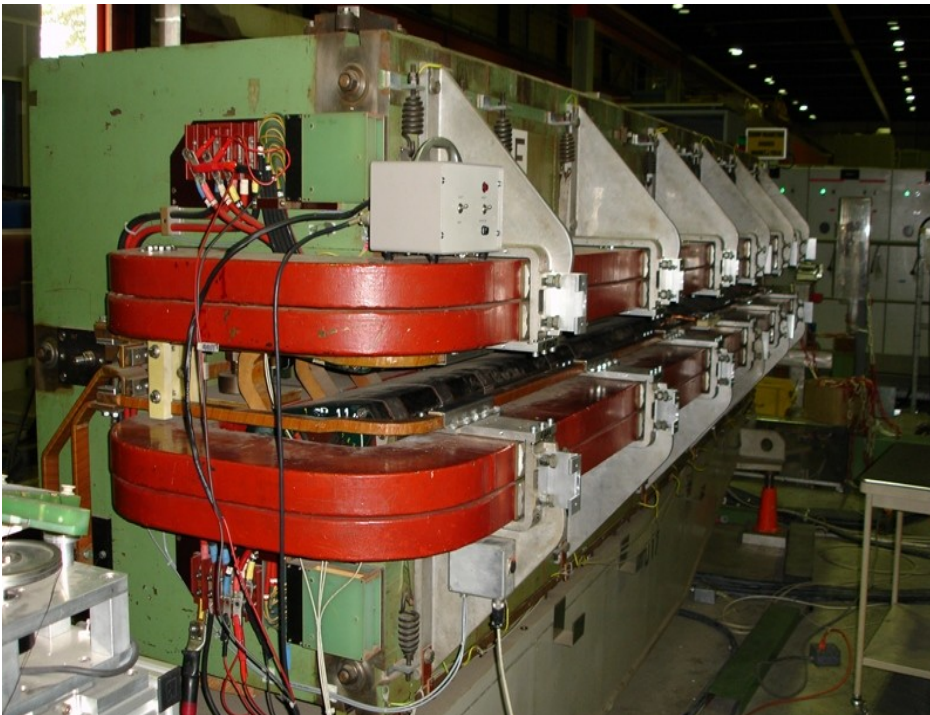
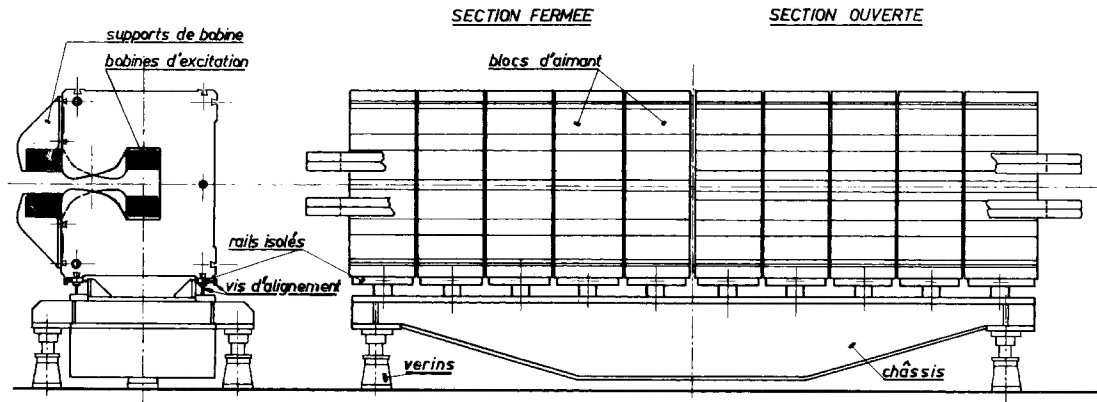


- Some basic considerations:
 - **Stability:** “What are the required stabilities on Q/ξ ?”
 - **Controllability:** “Can Q/ξ be controlled without 'hidden parameters'?”
 - **Observability:** “Can we measure Q/ξ (and also C^-) robustly?”
 - will comment on staged implementation, steps and possible performance

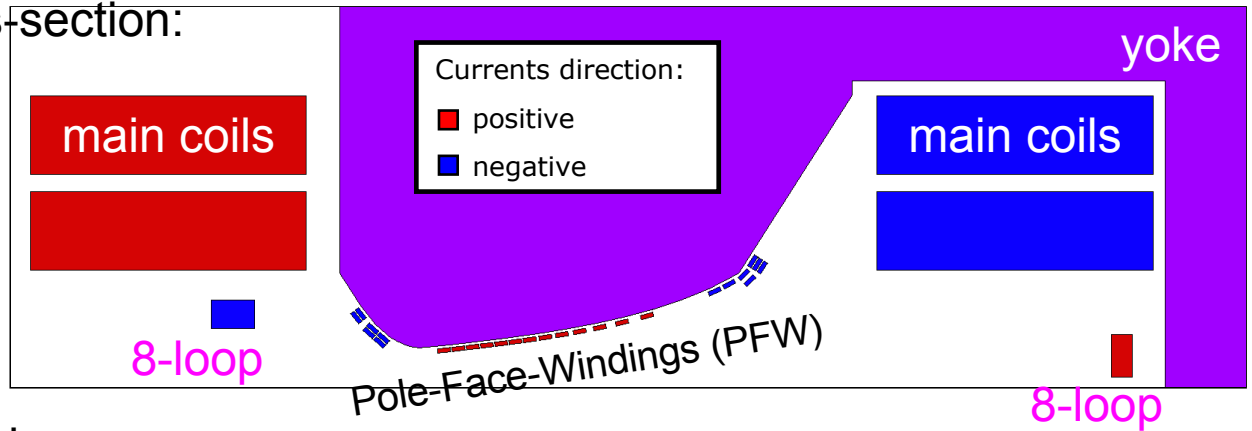
- Discussion with OP/ABP (Rende, Yannis):
 - main outcome: inconclusive, since most beam parameter (orbit, tune, chromaticity) have/could not be measured systematically in the past
 - most tight requirements during resonant extraction (slow, MTE) $10^{-3} \dots 10^{-4}$
 - otherwise: “keep the beam in the pipe”
 - minimisation of resonances, transition crossing, ...
 - to be kept in mind: the PS was/is running without beam-based feedbacks on orbit, tune, coupling and chromaticity for ~ 50 years
 - ... still the slow extraction worked.
 - preliminary: $\Delta Q \sim 10^{-2} \dots 10^{-3}$, $\Delta \xi \sim 0.1 \dots 0.2$ units?? (\sim SPS/LHC!?!)
 - time-scales are unclear – working assumption: \sim SPS (in turn scale!)
- (Ongoing) observation with beam required to quantify PS reproducibility and to cross-check real requirements with physics model prediction
- N.B. “Requirements” are tighter than what is actually achieved in the PS. Many PS cycle show tune stabilities in the order of a few percent (see measurements)

Controllability: PS' Combined Function Magnets - Pole-Face-Winding (PFW, since 1978) I/IV

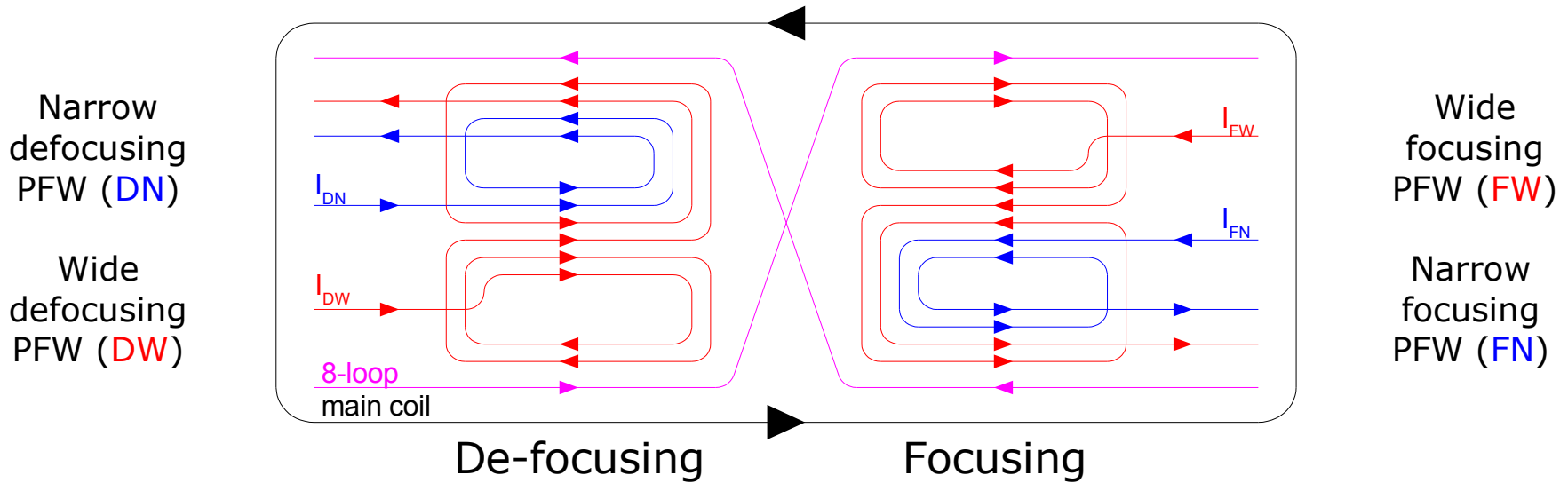
- “Recent” 5-current mode implementation eliminates hidden parameters and enables independent control of $Q_{H'}$, $Q_{H''}$, ξ_H and ξ_V



- Main-magnet cross-section:



- Main-magnet top-view:



- 2x Defocus. (DW, DN), 2x Focus. (FW, FN), 8-loop (~octupole) → 5 circuits
 - orthogonal control of: Q_x, Q_y, ξ_x, ξ_y

- Response can be cast into beam matrix form, e.g.:

$$p \cdot \begin{pmatrix} \Delta Q_H \\ \Delta Q_V \\ \Delta \xi_H \\ \Delta \xi_V \end{pmatrix} = \begin{pmatrix} +0.0647 & +0.0662 & -0.0352 & -0.0437 \\ -0.0345 & -0.0444 & +0.0641 & +0.0668 \\ +1.7909 & -0.3109 & +1.0416 & -0.2016 \\ -1.2220 & +0.1820 & -1.4866 & +0.3066 \end{pmatrix} \cdot \begin{pmatrix} \Delta I_{FN} \\ \Delta I_{FW} \\ \Delta I_{DN} \\ \Delta I_{DW} \end{pmatrix}$$

- source: R. Gouiran, CERN/PS/SM 76-1, ΔI_{xx} [A], p [GeV/c], $p < 15$ GeV/c
- Iron yoke saturation makes matrices slightly momentum dependent
 - differences per matrix element are small: $< 10\text{...}20\%$
 - does not pose a big problem for feed-back systems
- Main issues/concern:
 - Large differences ($>100\%$) between model and measured response matrix
 - Assumes small betatron-coupled machine
 - Most PS cycle at least partially coupled
(quality of 5-current MD reponse matrix data?)

→ Any orbit, Q or Q' control requires also control/minimisation of coupling!

Controllability: PS' Combined Function Magnets - Circuit and PFW Time-Constants

- natural time constants ~ 2 ms (wide) and ~ 9 ms (narrow) resp.
(wide: $R = 1$ m Ω , $L = 2$ mH; narrow: $R = 2.1$ m Ω , $L = 17$ mH)
 - natural circuit bandwidth ~ 125 Hz
- PFW are by ± 1200 V/ ± 250 A power converters ($|\Delta I/\Delta t|_{\max} = 5$ kA/s)
 - Driven “large signal” bandwidth: ~ 125 Hz
($\Delta I \sim 50$ A \leftrightarrow $\Delta Q \sim 0.1$ @26 GeV/c)
 - Driven “small signal” bandwidth: > 1 kHz (theoretical)
($\Delta I \sim 5$ A \leftrightarrow $\Delta Q \sim 0.01$ @26 GeV/c, noise: ~ 50 mA \leftrightarrow $\Delta Q \sim 10^{-4}$)
- Main limitations:
 - non-linearities due to current rate-limit (similar to LHC PC \rightarrow easy for FB control)
 - PC sampling frequency ($f_s = 1$ kHz) limits effective Q-loop bandwidth, typically: $f_s \approx 25 \dots 40 \cdot f_{bw}$
 - thus, from controllability point of view only Q-loop BW': $f_{bw} < 40$ Hz
 - or: if $f_{bw} := 100$ Hz $\rightarrow f_s > \sim 4$ kHz

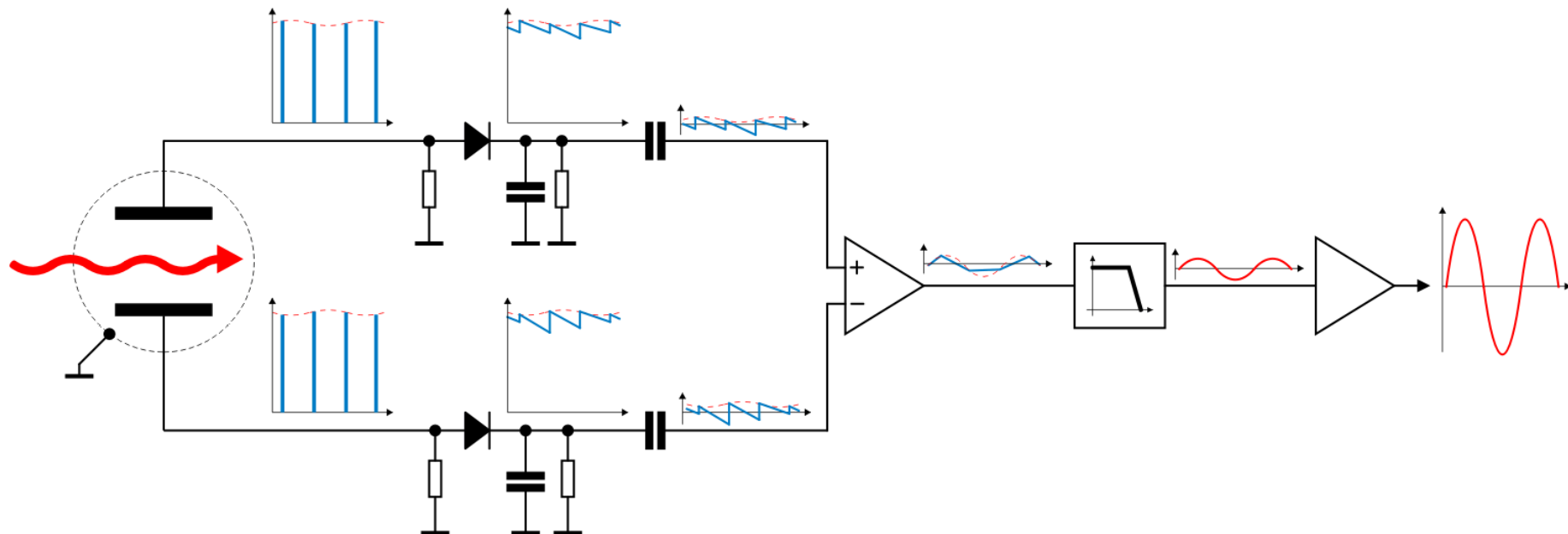
- Common approach:
 - Same diode based detection
 - Same digital acquisition system
 - Based on DAB64x
 - developed by TRIUMF (Canada) for the LHC BPM/BLM systems
 - Mezzanine cards house ADCs adapted for machine revolution frequency
 - Same FESA and BI-expert diagnostic tool chain for all CERN accelerators

- Full BBQ acquisition chain available in PS/PSB since beginning of September



PS (section 72)

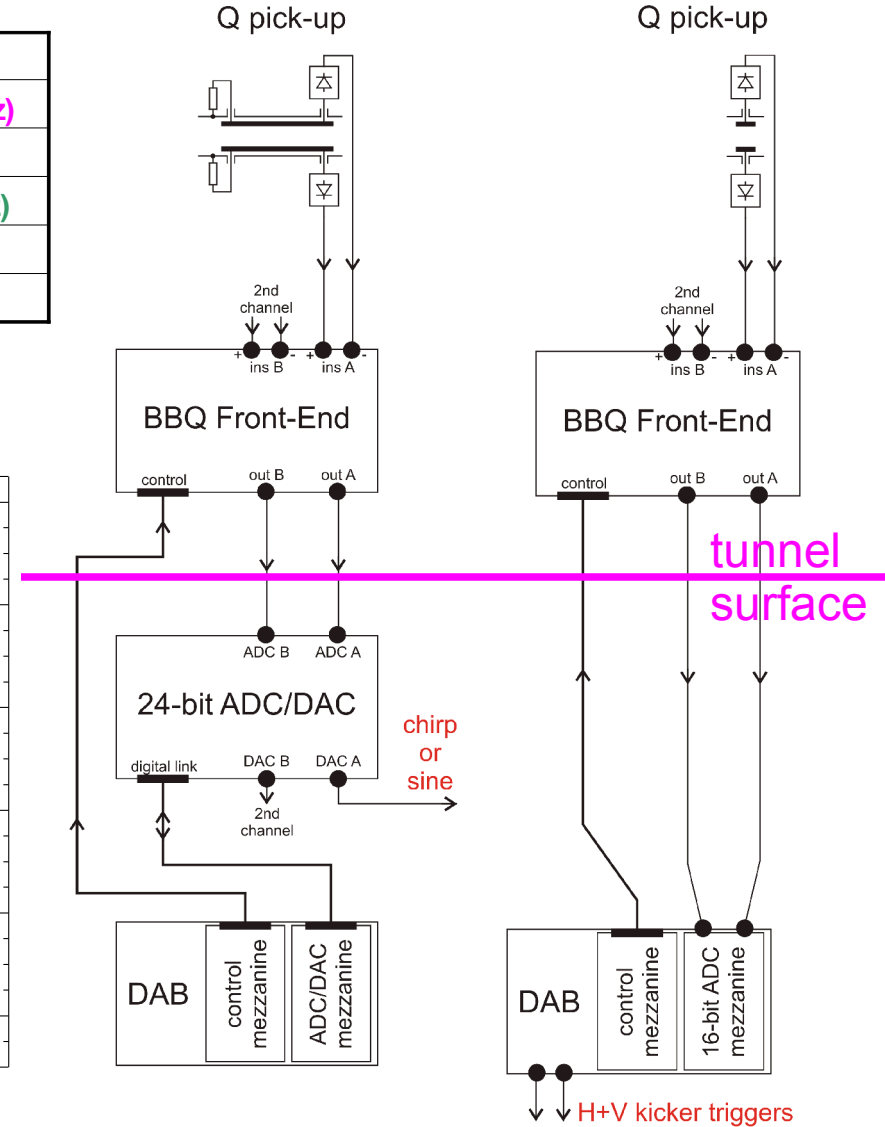
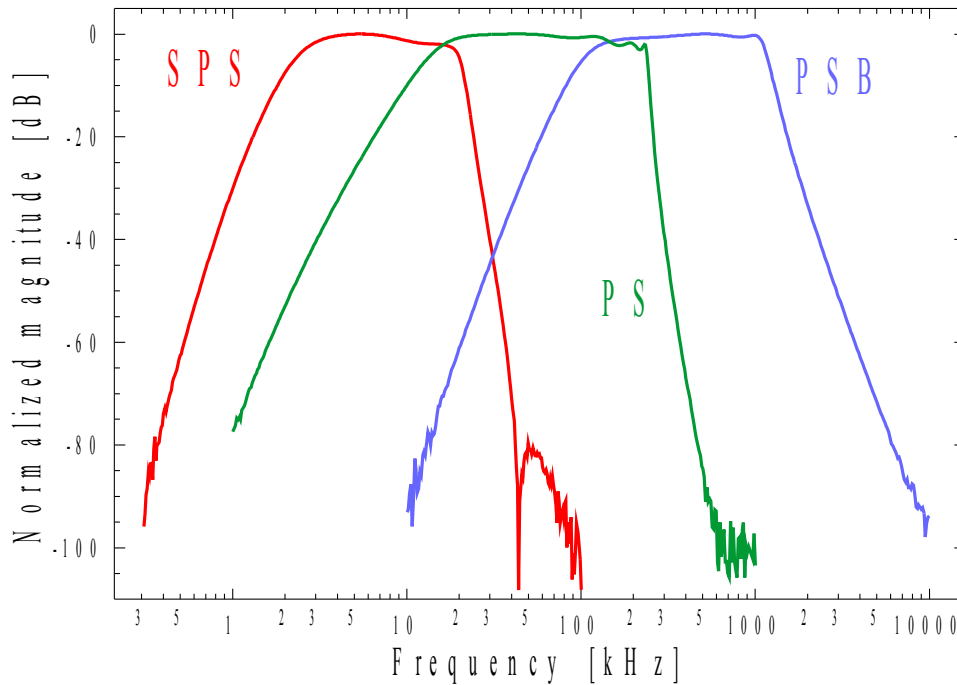
- Detection principle (*M. Gasior, "CERN-LHC-Project-Report-853"*):



- Peak detection of position pick-up electrode signals (“collecting just the cream”)
- Revolution frequency content converted to the DC and removed by series capacitors
- Betatron modulation moved to low frequency range (it is carried by much longer pulses)
- Impossible to saturate (large f_{rev} suppression already at the detectors + large dynamic range)
- Large sensitivity
- Low frequency operation
 - high resolution ADCs available
 - Signal conditioning / processing is easy (powerful components for low frequencies)
- “New” additional modifications: low-pass filtering in order to reduce longitudinal RF noise (N.B. any transverse pickup is intrinsically sensitive to both longitudinal and transverse spectra.) 9/21

Observability - BBQ Systems at CERN

Machine	Front-End	Acquisition
LHC	"constant f_{rev} type"	24 bits (up to 100 kHz)
SPS	"constant f_{rev} type"	24 bits
PS	"constant f_{rev} type"	16 bits (up to 40 MHz)
LEIR	"varying f_{rev} type"	16 bits
PSB	"varying f_{rev} type"	16 bits



Some measurements with beam in the PS available

- Preliminary observations:

- seems to be compatible with PS' “RF-gymnastics” at least with those seen on the [SFTPRO](#), [CNGS](#), [EASTB](#), [LHC25ns](#) and [MD2](#) cycle (see plots)
- in contrast to SPS: no “tune-spectra-guarantee” without excitation
→ kicks (though they can be small) seem to be mandatory
- works with un-bunched beam (see attachment)
- transparent to slow bunch length variations
- of course: **further tests/optimisation are required and will be done!**

- Outstanding Issues (in progress):

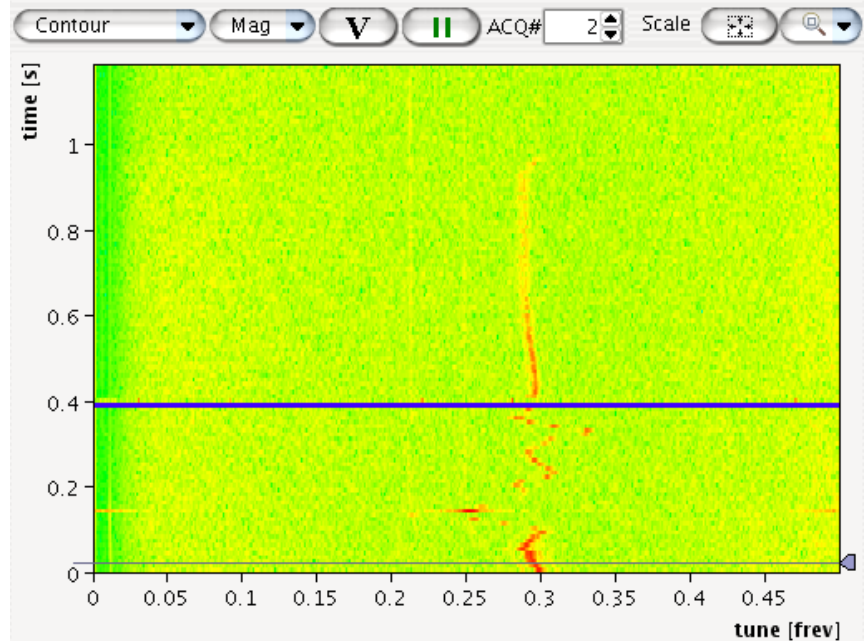
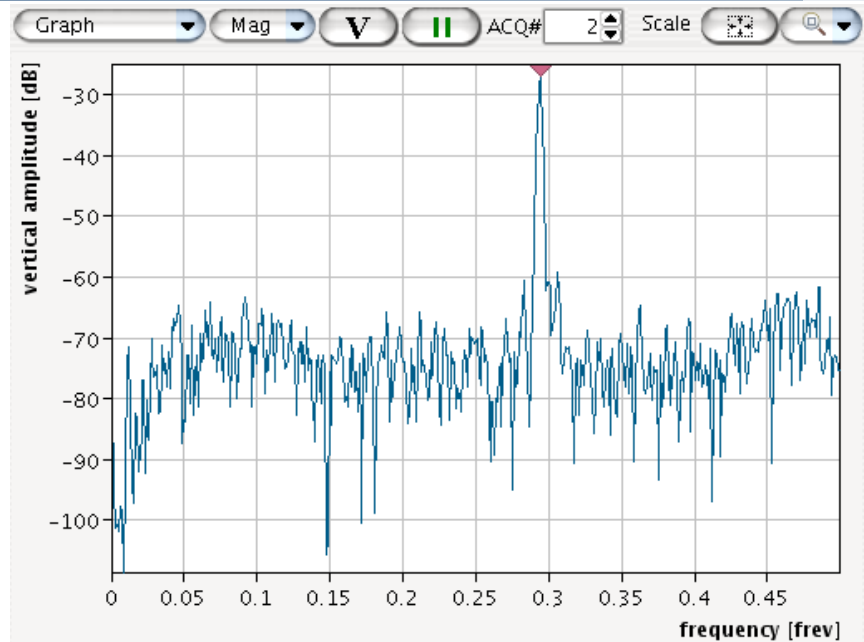
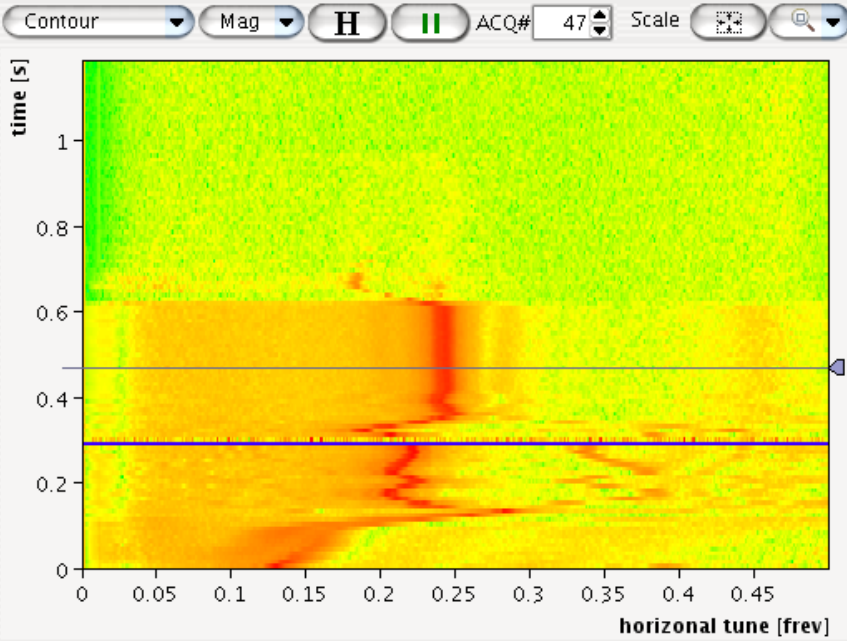
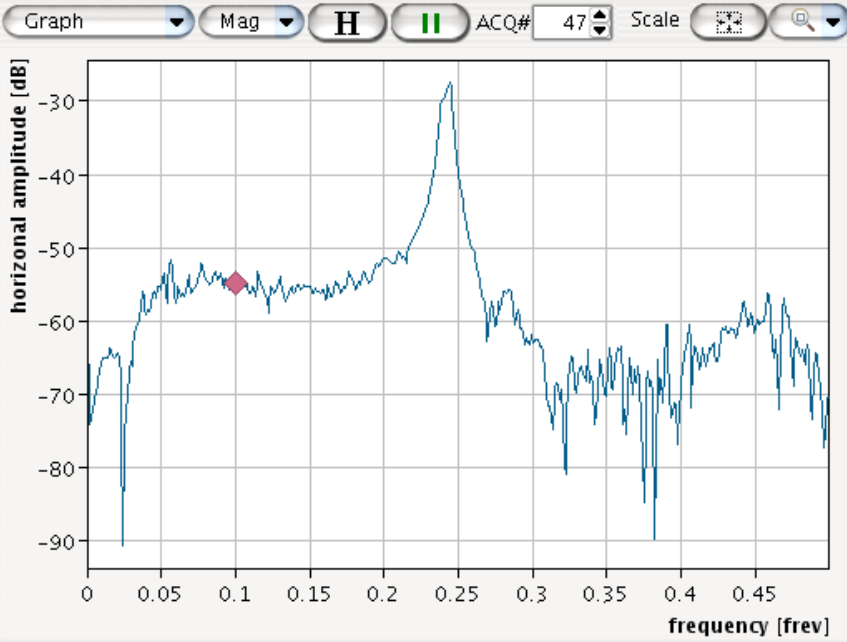
- excitation chain is controlled in a different way on each machine
 - (re-design) of PS/PSB kicker amplitude control
 - re-phasing of kick vs. bunch arrival (mainly for single ion bunch beams)
- S/N improvements for low-signal beam (= small bunch-peak signals)
 - single ion bunches are at the limit but visible

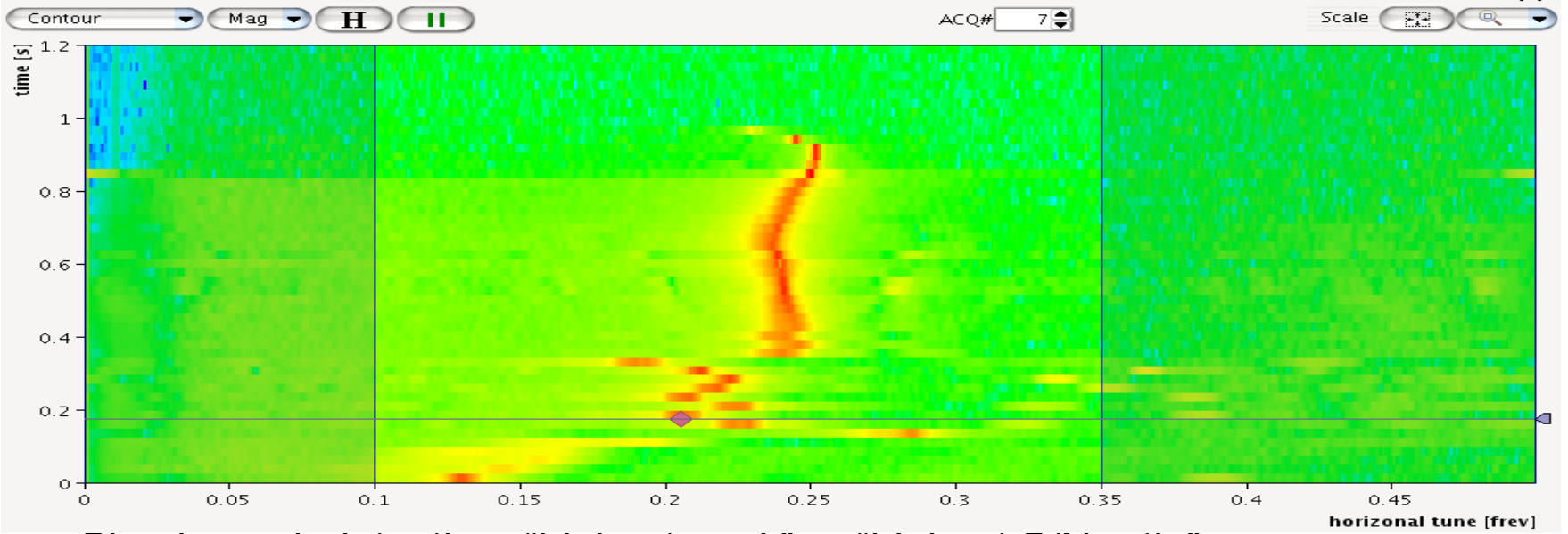
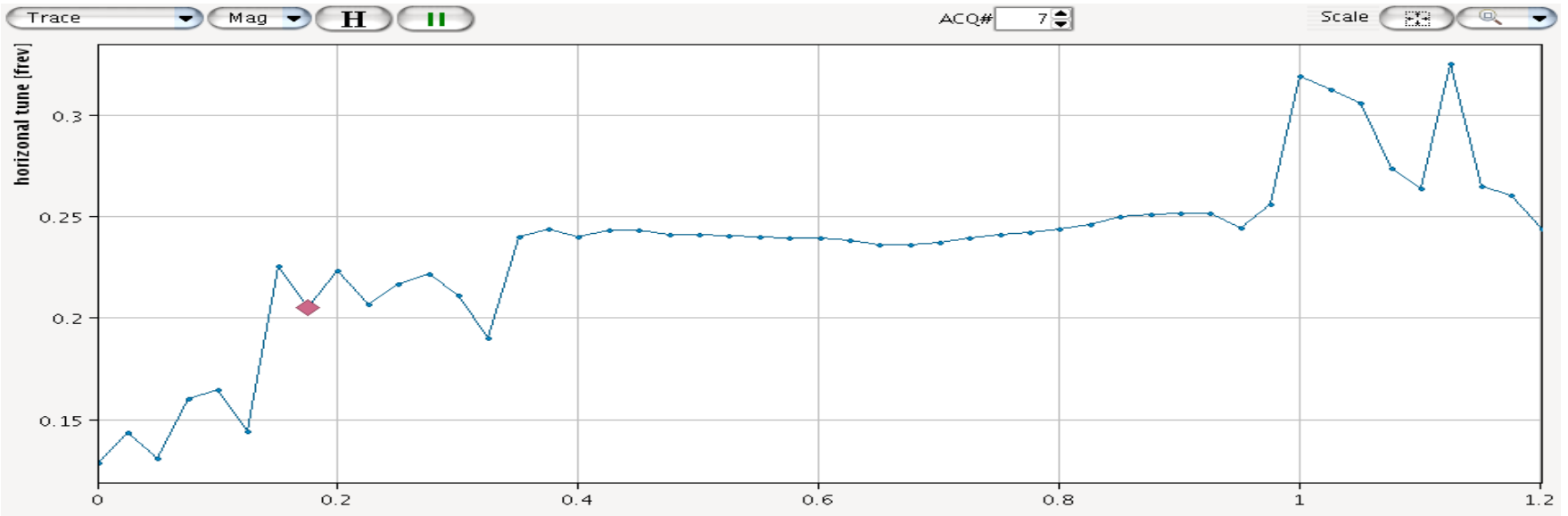
- **Most of these issues are driven by the large observed ΔQ ($\sim Q'$) variations**

DAB based BBQ acquisition: PS examples

PS-MD2, H/V kicks, "free-running mode"

Feasibility of (semi-) automated Tune Control in the PS, Ralph.Steinhaugen@CERN.ch, APC 2007-09-28





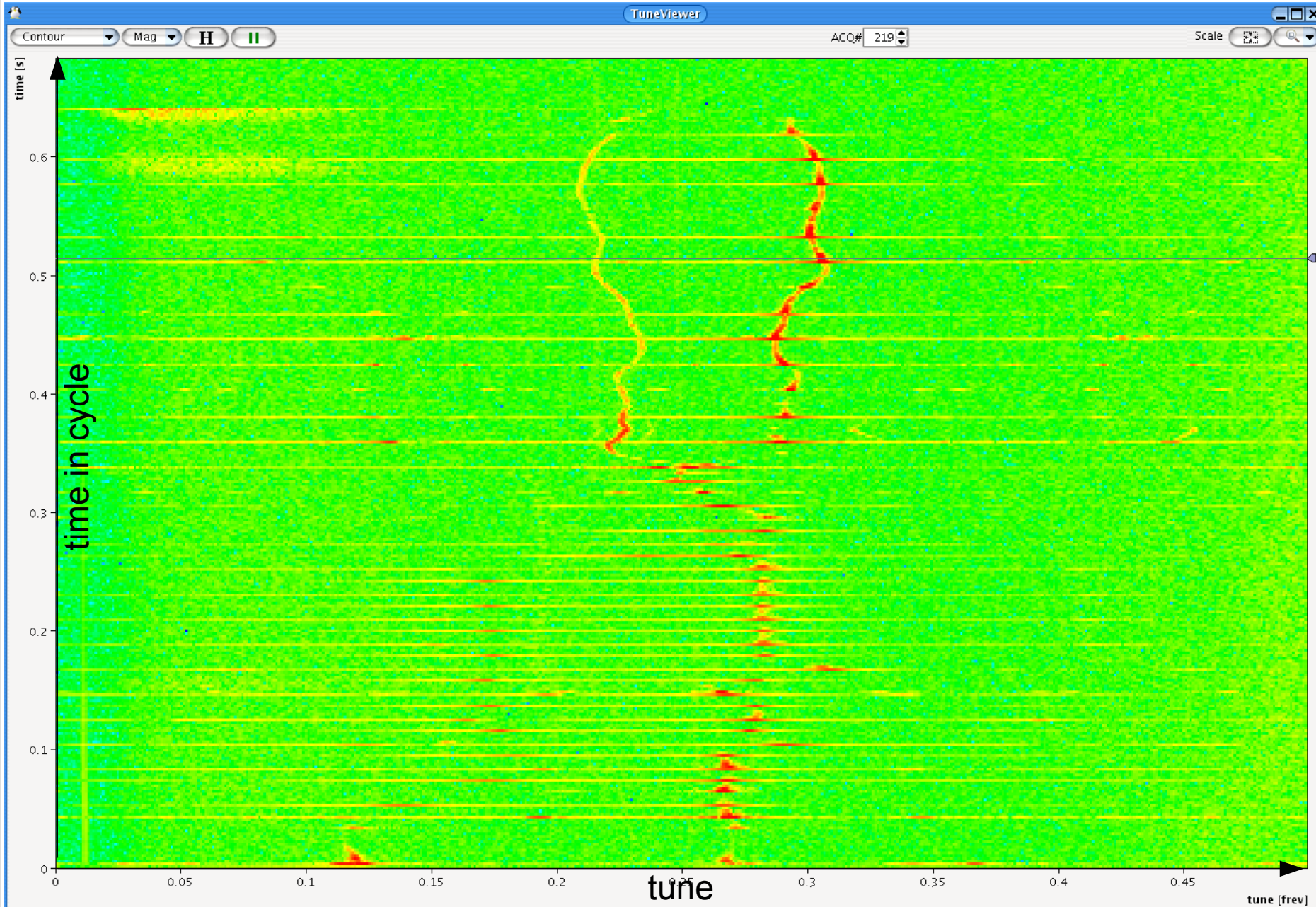
■ Simple peak detection: “highest peak” or “highest S/N ratio”



PS-SFTPRO cycle, back-to-back acquisition, H/V kicks every 5 ms, horizontal plane



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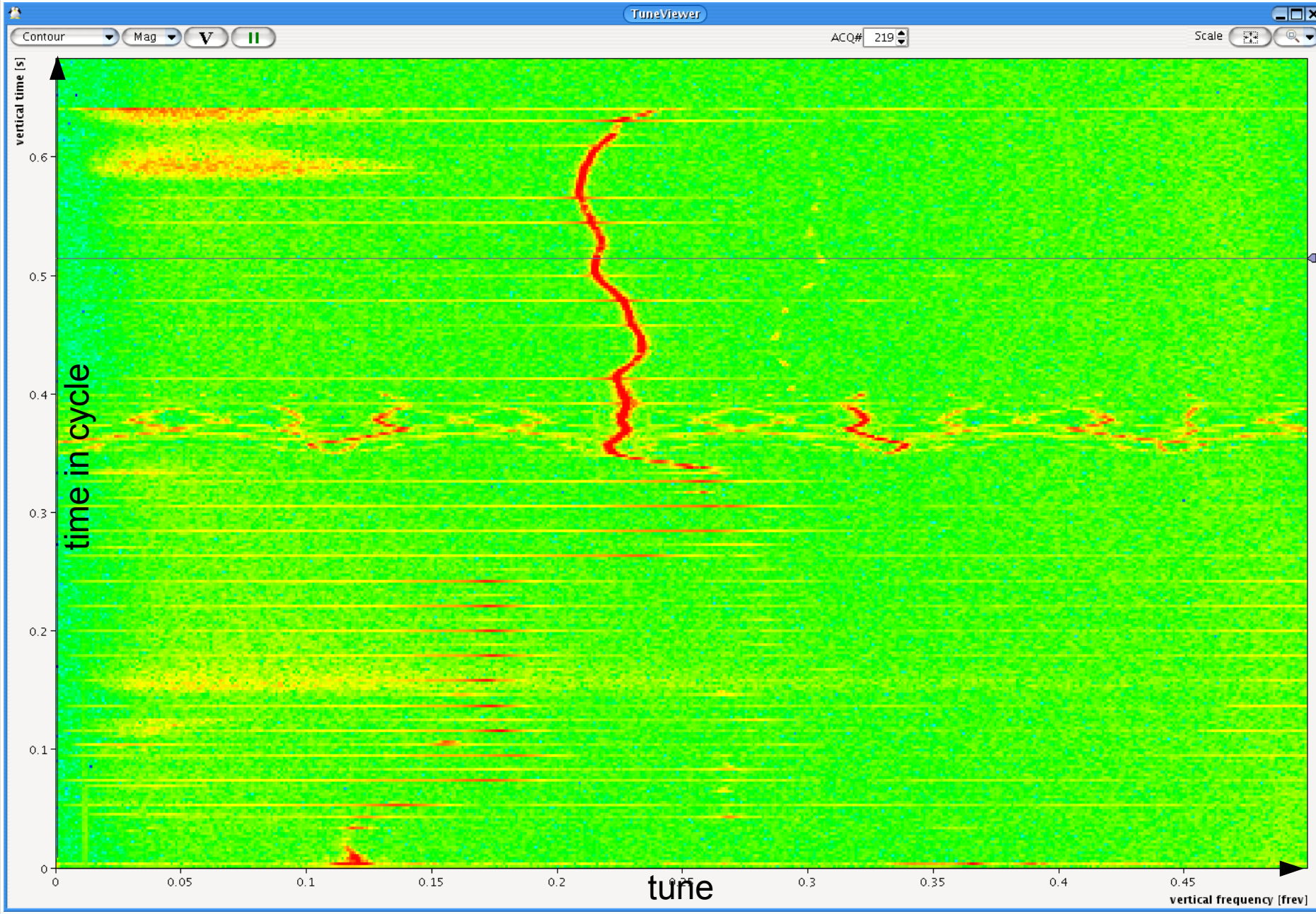




PS-SFTPRO cycle, back-to-back acquisition, H/V kicks every 5 ms, vertical plane



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PS-SFTPRO cycle Betatron-Coupling after Injection

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File Configure
Tune Viewer
Help

Acquisition Settings

Machine cycle: + off-line

Acquisition Length [turns]: 1024

Measurement Rate (Period): 25 Hz (40 ms)

Start [ms]: 0

Stop [ms]: 0

Type of Excitation: OFF

get set

Excitation Tune Fitter Misc

Q_x = .1000 Q_y = .2695
@T_c = 51 ms

Comments: Detach Viewer

▶
▶
▶
⏸
⏹

Contour
Mag
H
⏸
ACQ# 22
Scale

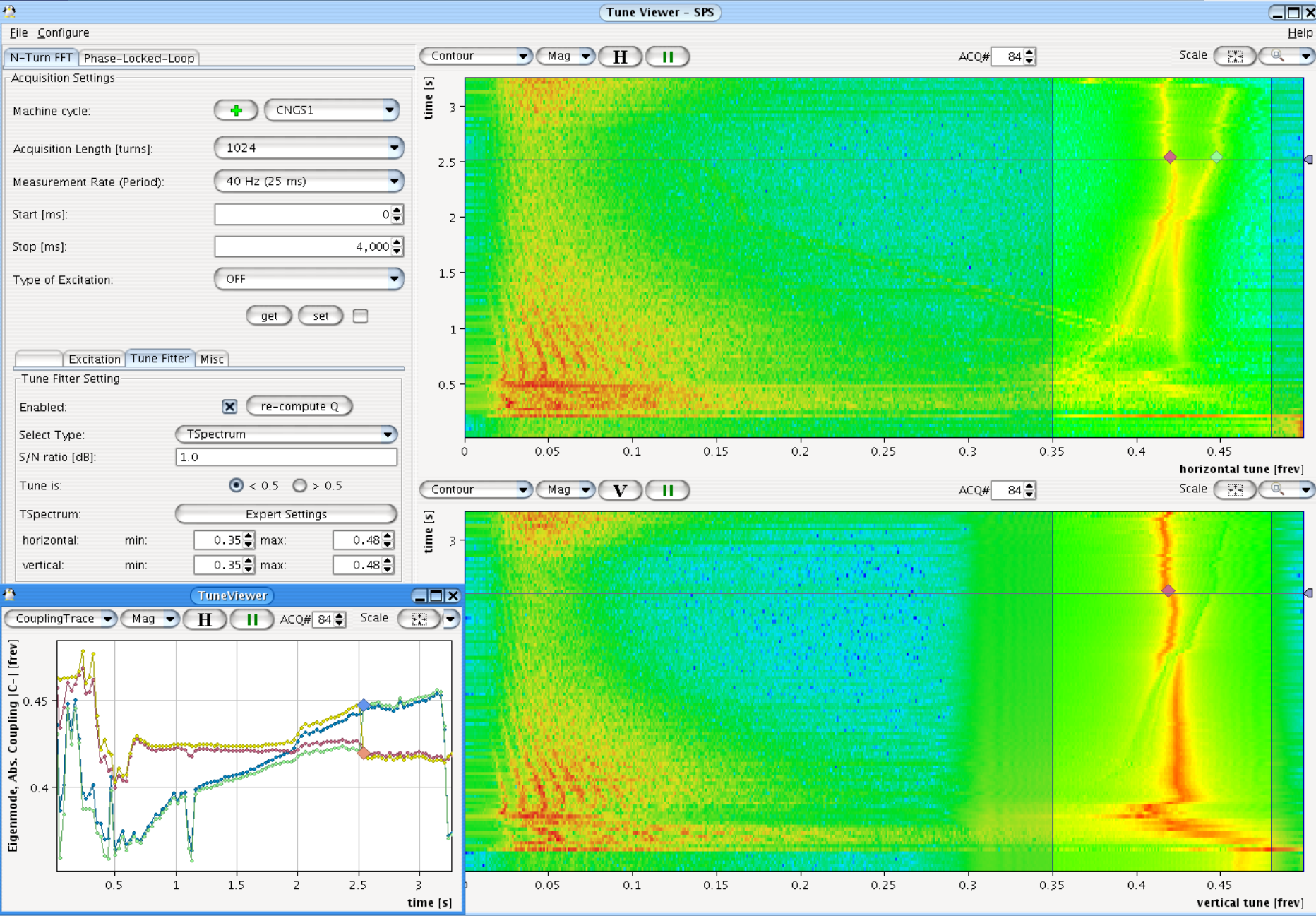
Graph
Mag
H
⏸
ACQ# 22
Scale

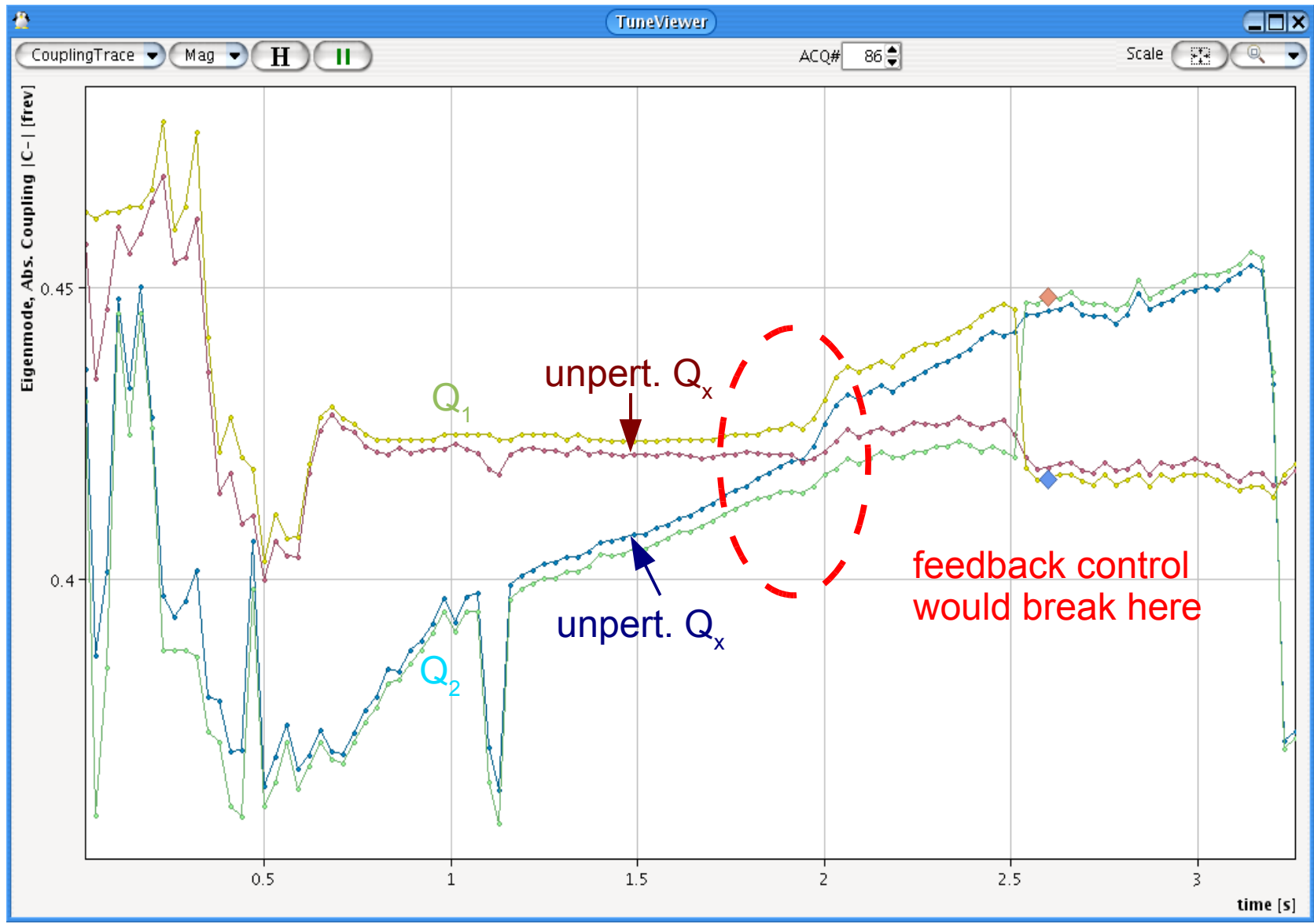


Betatron-Coupling: CNGS1 (SPS) I/II



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What if.... (the nearish future) I/II

- Provided that betatron-coupling is not required and minimised to zero....
- ...a semi-automated slow 'cycle-to-cycle' feedback control could
 - correct for fast intra-cycle perturbations due to
 - current overshoots, b_1/b_2 mismatches, ramp systematics, ...
 - correct for slow environmental induced cycle-to-cycle perturbations:
 - girder movements, temperature drifts of magnetic fields (iron), slow intensity variations, ...
 - be useful for the fast setup of new user/cycles
 - reach an “intra-cycle” correction bandwidth” of $\sim 100\text{-}200\text{ Hz}$
 - possible implementation:
 - could be based on the already available BBQ instrumentation (the necessary tools are there!)
 - top-level GUI that performs an automated measure-and-correct principle using chirped FFT data
 - e.g. 1024 turn-FFT every 5 ms
 - similar to what is known in the SPS as 'Auto-Pilot' in case of trajectory/orbit steering

What if.... (the far (far?) away future) II/II

- Provided that betatron-coupling is not required and minimised to zero....
- ...a fully-automated intra-cycle feedback control could in addition
 - correct for fast intra-cycle perturbations due to:
 - power converter (mains) harmonics,
 - fast intensity driven tune changes (beam loss + impedance)
 - other 'truly random'/incoherent noise sources
 - reach a feed-back bandwidth of ~ 100-200 Hz
(provided PC sampling frequency is increased to 4 kHz (to minimise PID phase lag))
 - possible implementation:
 - PLL is not the ideal candidate for a robust Q-loop in the PS since RF bunch splitting, gymnastics, coupling and other effects 'skews up' the beam-transfer function which is required to be reasonably stable
 - Propose: (narrow bandwidth) chirp-based excitation with continuous FFT detection is preferable (e.g. 1024-turn FFT every 100 turns)
 - robust peak-detection needs further assessment
 - control logic could be fairly easily implemented within a FPGA once the digital power converter input interface is established

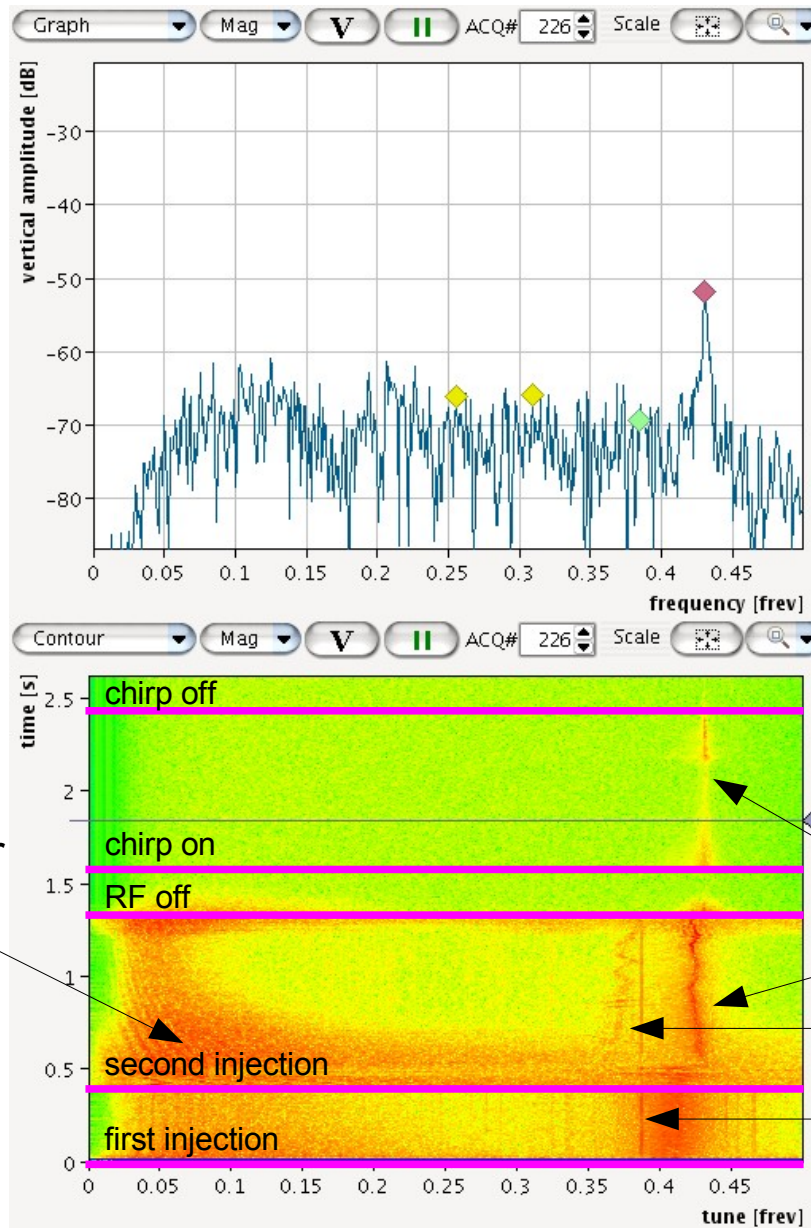
- The actual implementation of the five current scheme enables (new) possibilities for the control of tune and chromaticity in the PS
 - requires control/minimisation of coupling!

- However the need and/or requirements for a fast Q-loop control are unclear

- Proposed feedback implementation/deployment steps:
 - 1. Quantification of parameter requirements based on robust measurements (ongoing)
 - 2. Semi-automated cycle-to-cycle feedback control
 - could reach a intra-cycle bandwidth of about 100-200 Hz
 - could be implemented on the basis of already available hard-/software
 - 3. Fully automated in-cycle feedback within in the Q-meter FPGA
 - could reach a true closed-loop bandwidth of about 100-200 Hz



additional supporting slides



RF + damper noise

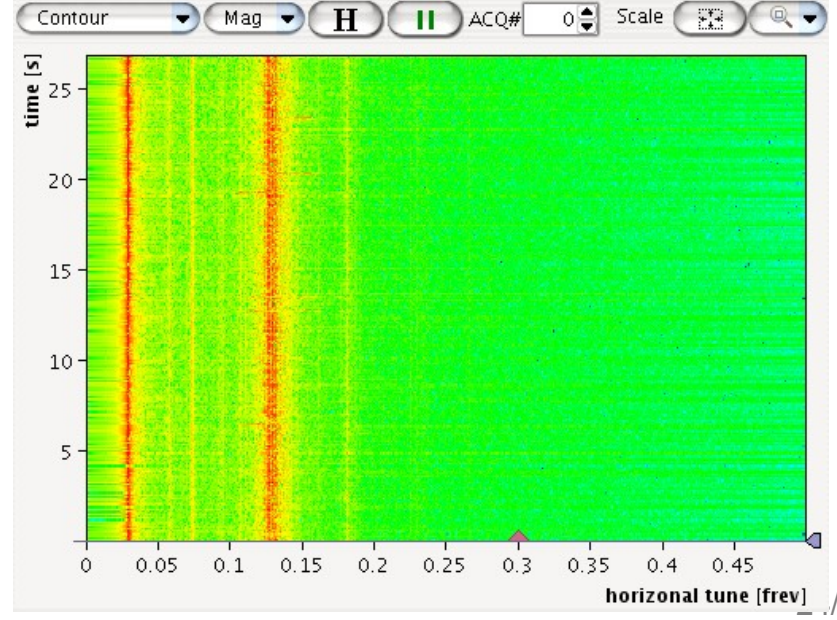
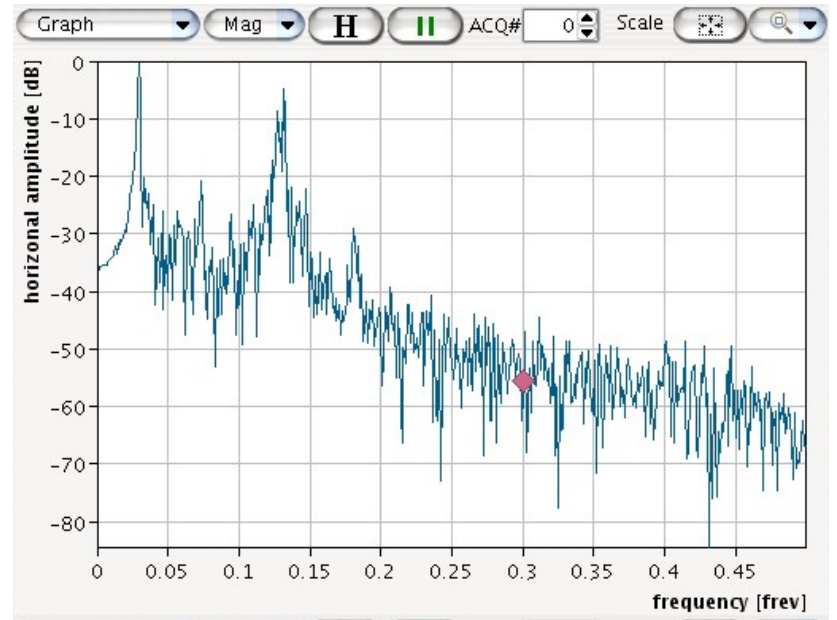
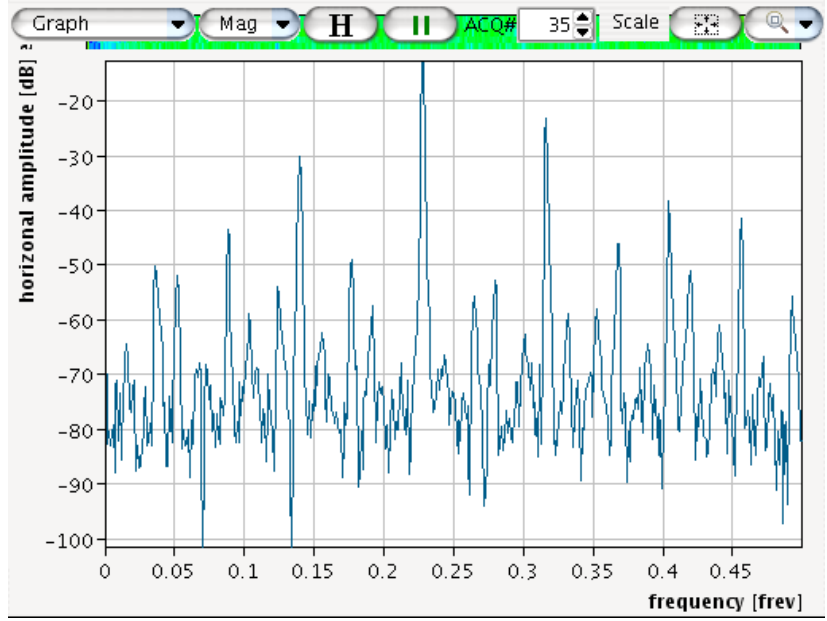
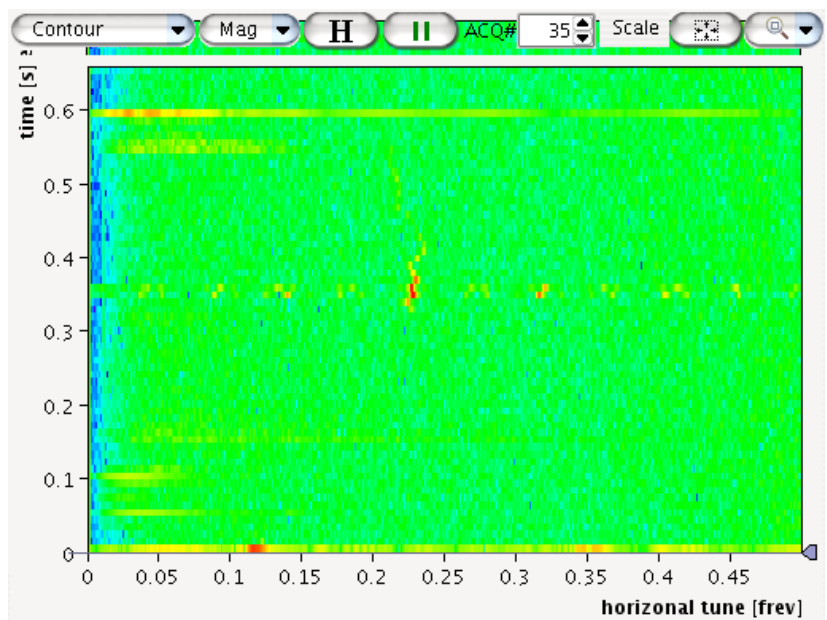
vertical tune

horizontal tune

damper noise

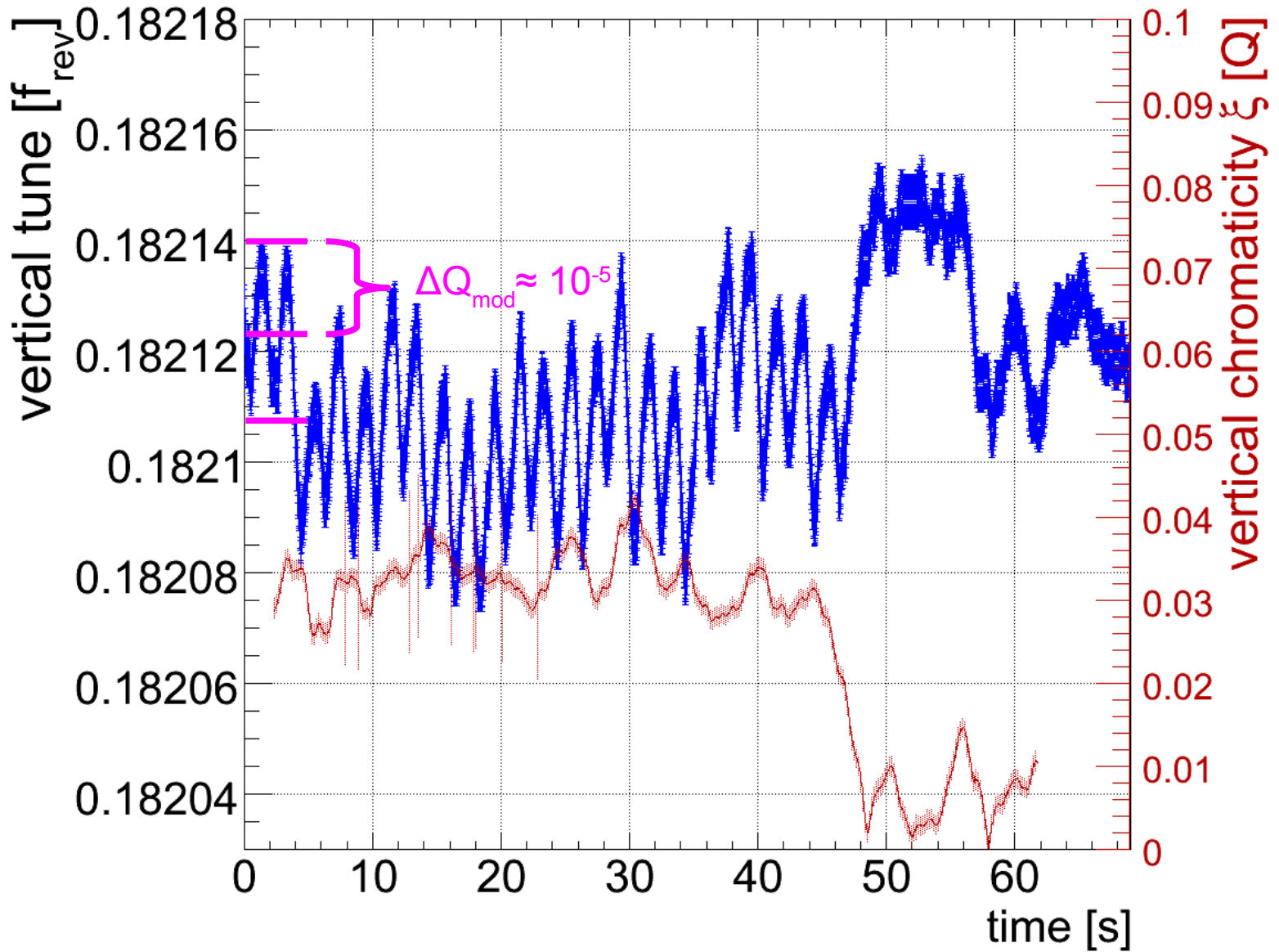
PS-SFTPRO(1) cycle

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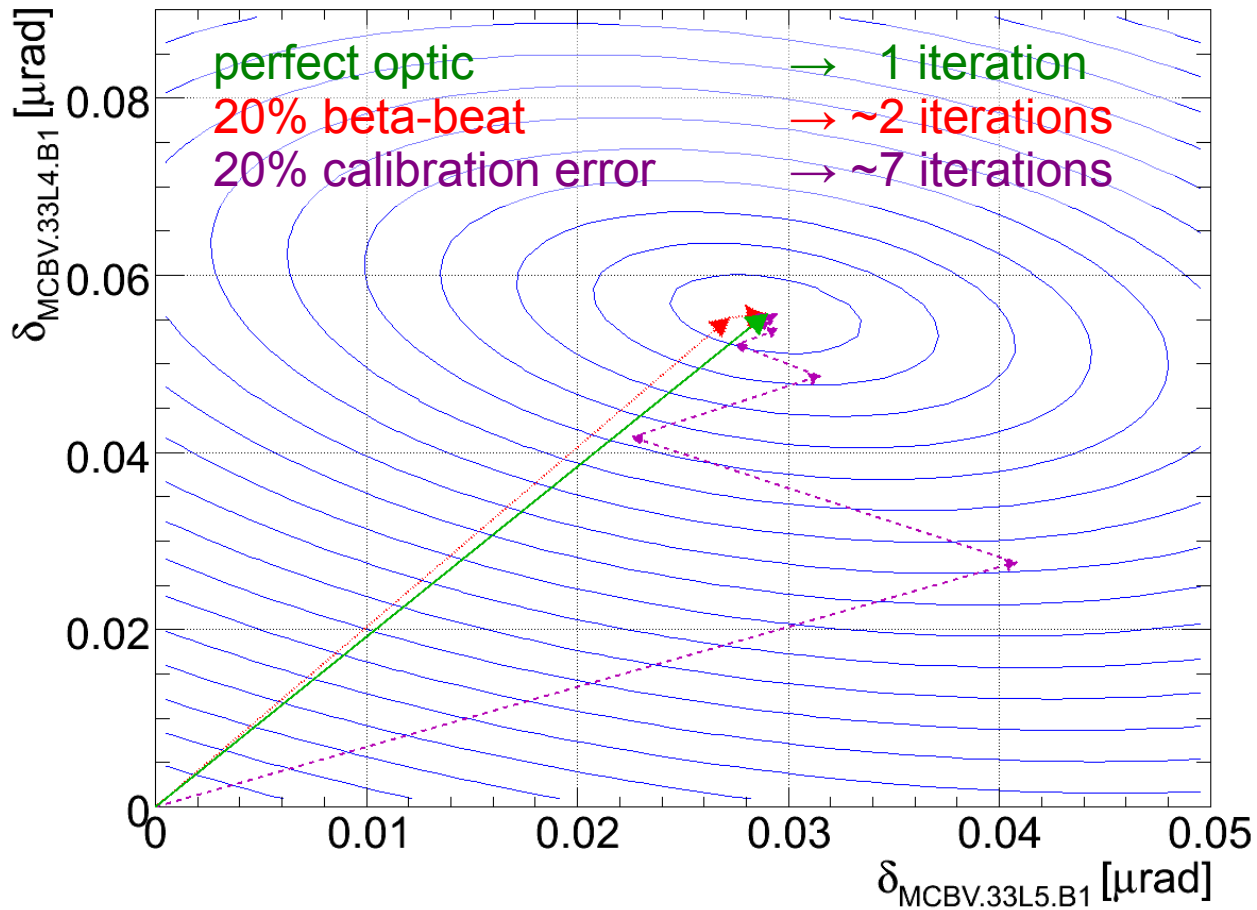
HOT: SPS Q' tracking study

Radial RF modulation $dp/p=1.6 \cdot 10^{-5}$, set $\xi := 0.05$

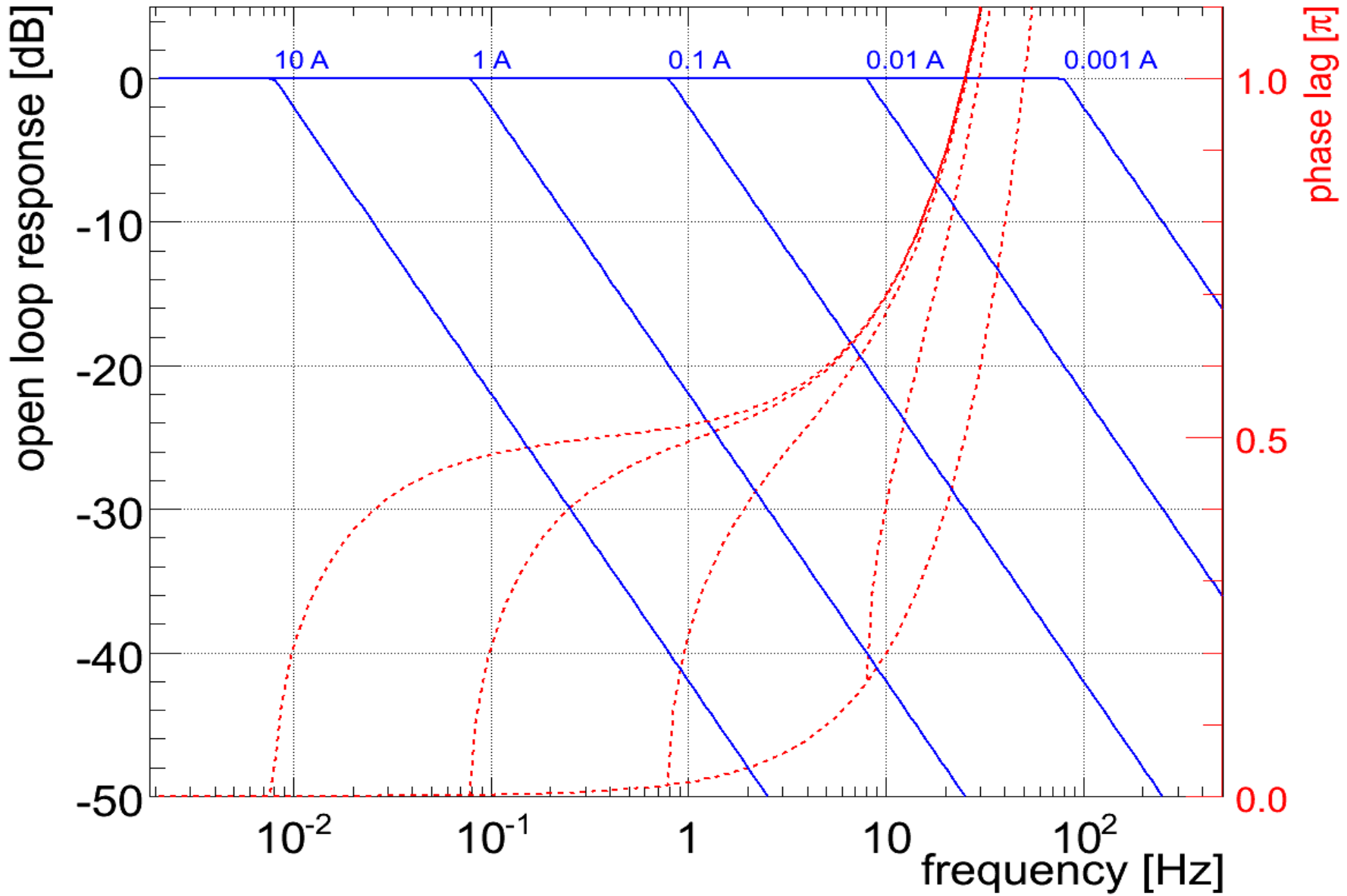


Q/ξ Beam Response Matrix Uncertainties

- Uncertainties in the beam response matrix reduced the effective control/feedback bandwidth but does not affect the steady-state precision
- E.g. LHC orbit feedback:



Non-linear Slew-rate Limited Exciter Response

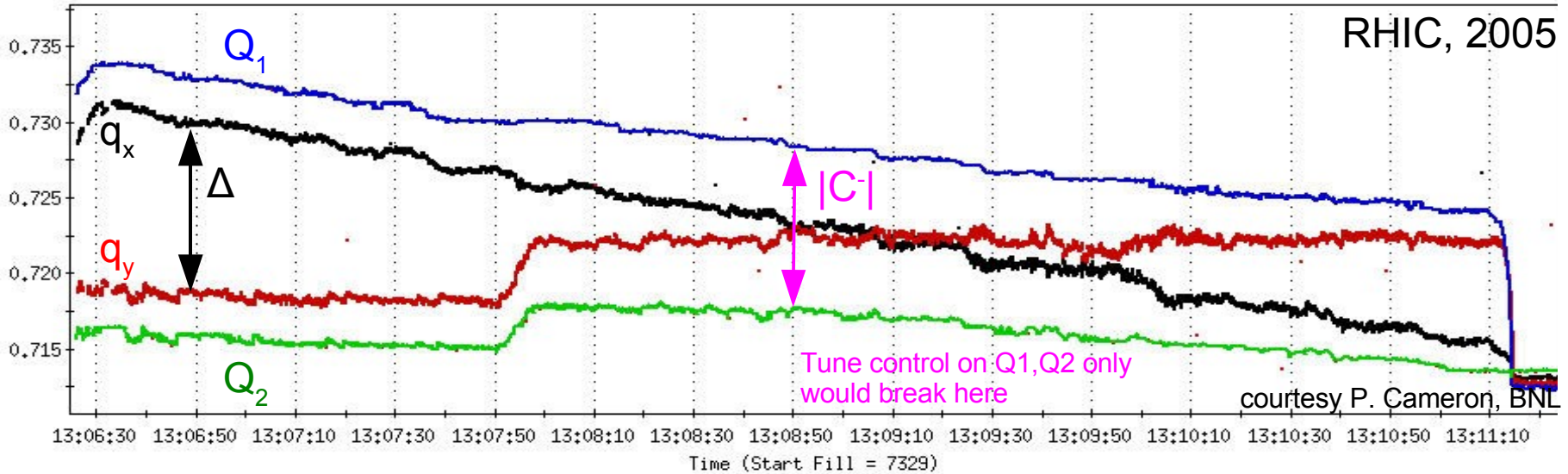


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LHC orbit dipole corrector: $\Delta I=0.01 \leftrightarrow \Delta x \approx 15 \mu\text{m} @7\text{TeV}$

- Strictly speaking: PLL measures eigenmodes (Q_1, Q_2) which in the presence of coupling may be rotated w.r.t. unperturbed tunes ($q_x, q_y, \Delta = |q_y - q_x|$):

$$Q_{1,2} = \frac{1}{2} \left(q_x + q_y \pm \sqrt{\Delta^2 + |C^-|^2} \right)$$



- Possible improvement:
 - optimise tune working point (larger tune-split),
 - vertical orbit stabilisation in lattice sextupoles,
 - active compensation and correction of coupling

Cross-Dependability and Constrains of FB Loops II/III

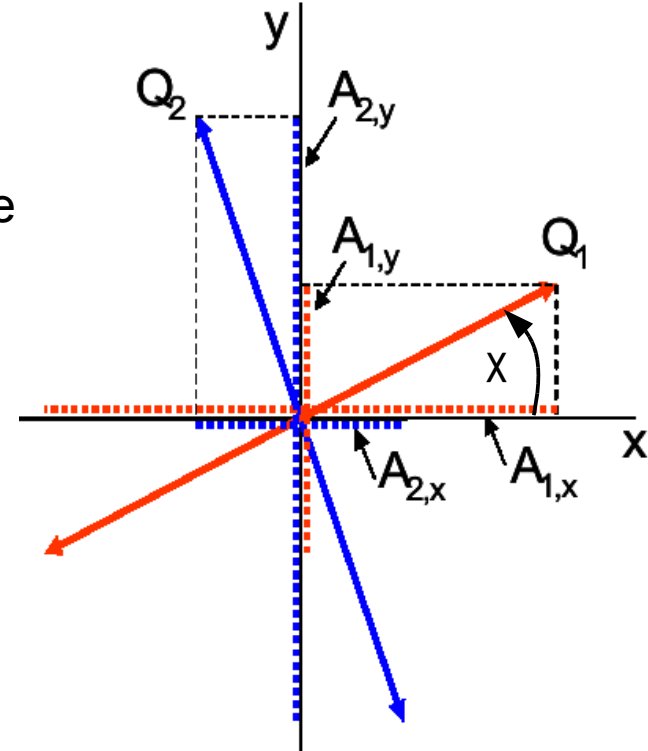
- Coupling III/II

- Measure ratio between regular and cross-term:
 - $A_{1,x}$: “horizontal” eigenmode in vertical plane
 - $A_{1,y}$: “horizontal” eigenmode in horizontal plane

$$r_1 = \frac{A_{1,y}}{A_{1,x}} \quad \wedge \quad r_2 = \frac{A_{2,x}}{A_{2,y}}$$

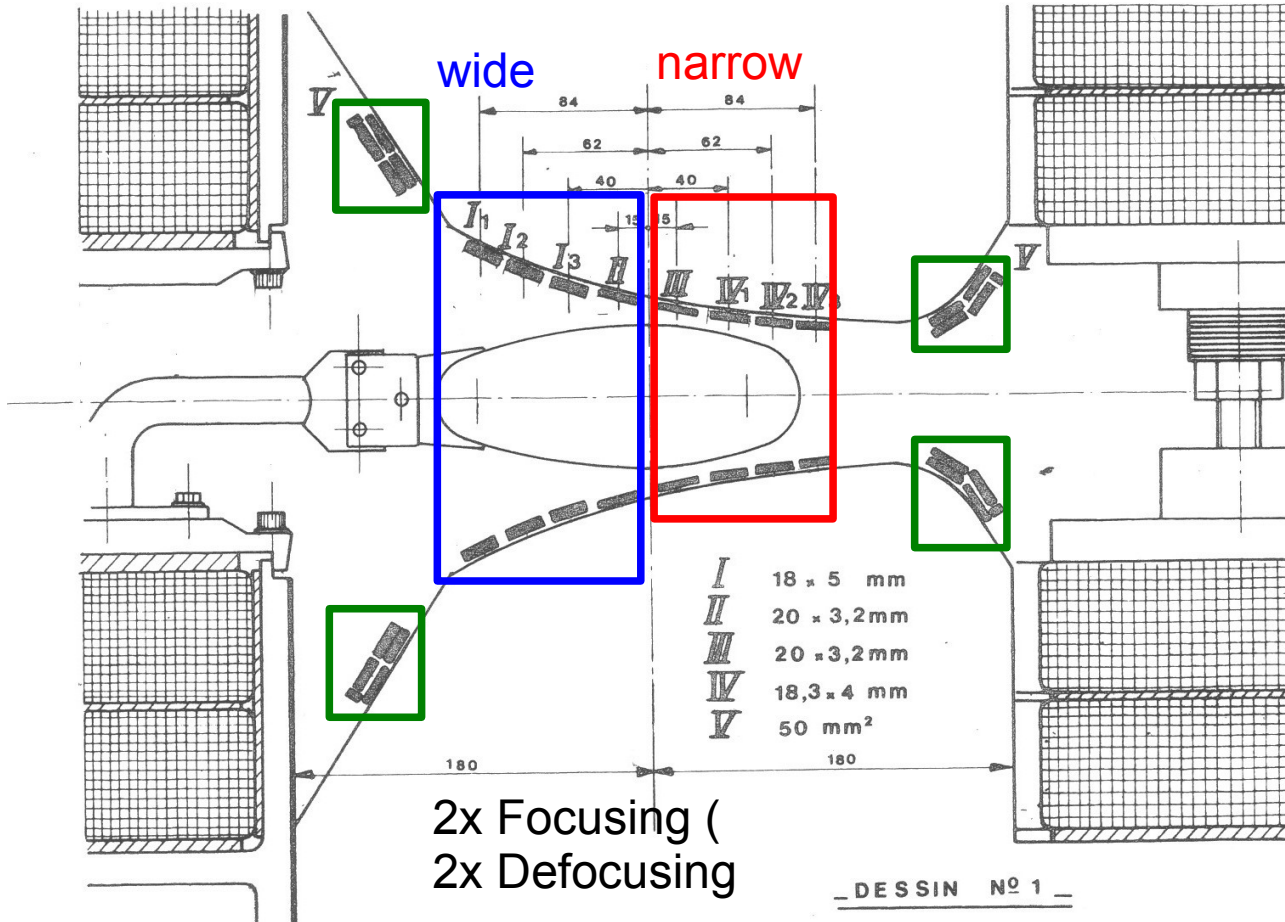
$$\Rightarrow \boxed{|C^-| = |Q_1 - Q_2| \cdot \frac{2\sqrt{r_1 r_2}}{(1 + r_1 r_2)} \quad \wedge \quad \Delta = |Q_1 - Q_2| \cdot \frac{(1 - r_1 r_2)}{(1 + r_1 r_2)}}$$

- Decoupled feedback control
 - $q_x, q_y \rightarrow$ quadrupole circuits strength
 - $|C^-|, \chi \rightarrow$ skew-quadrupole circuits strength



implemented and tested at RHIC

- Main Dipole's Pole-Face-Winding (PFW) Schematic (before 1978)



- 1x Focus. (FW, FN), 1x Defocus. (DW, DN), 8-loop (~octupole) → 3 circuits